

The Sentinel 1 missions

Launch: May 2013

Yves-Louis DESNOS, Ramon TORRES, Pierre POTIN, Betlem ROSICH,
Nuno MIRANDA, Dirk GEUDTNER

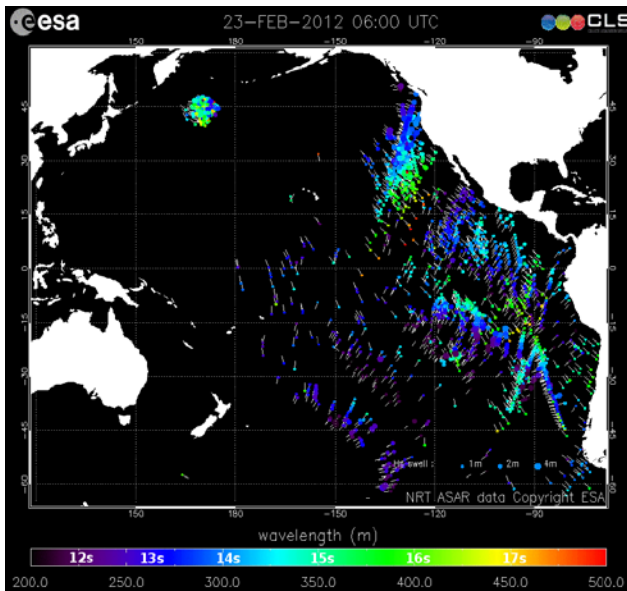
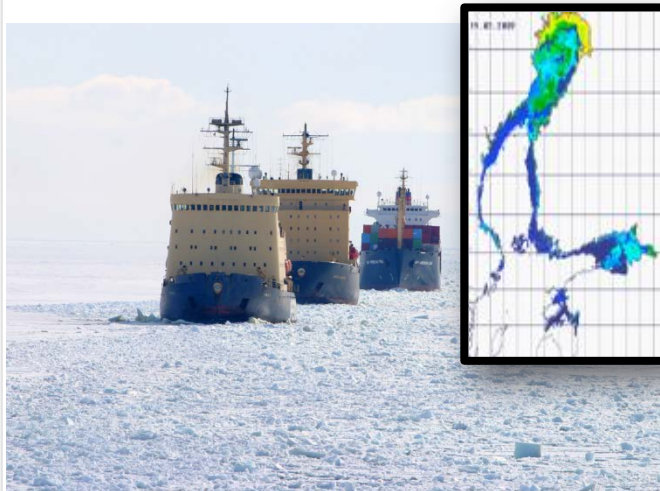
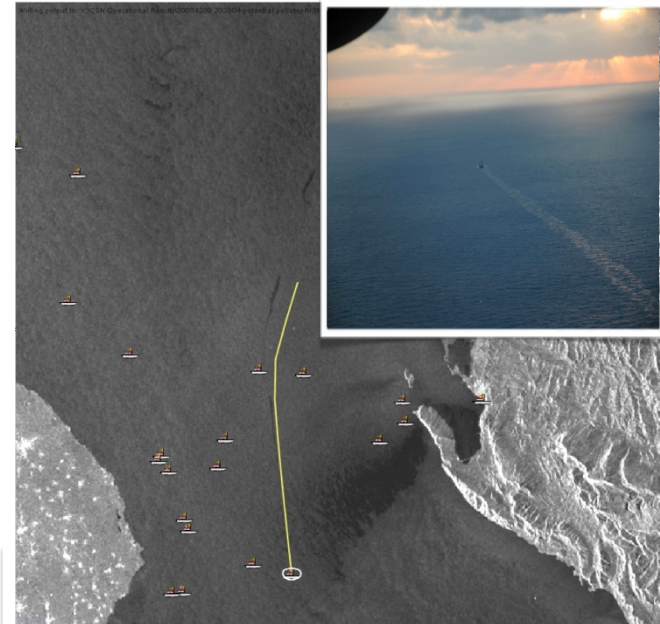
European Space Agency

Sentinel-1 Mission Objectives



Provide routinely and systematically SAR data to GMES Services and National services:

- ✓ Marine Monitoring (e.g. oil spill, sea ice)
- ✓ Land Monitoring (e.g. land cover, surface deformation)
- ✓ Emergency Response
- ✓ Climate Change (e.g. Polar caps incl. ice shelves and glaciers)
- ✓ Security (e.g. vessel detection)

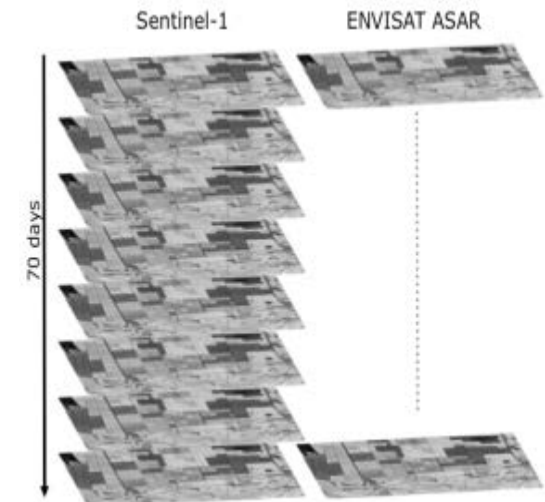
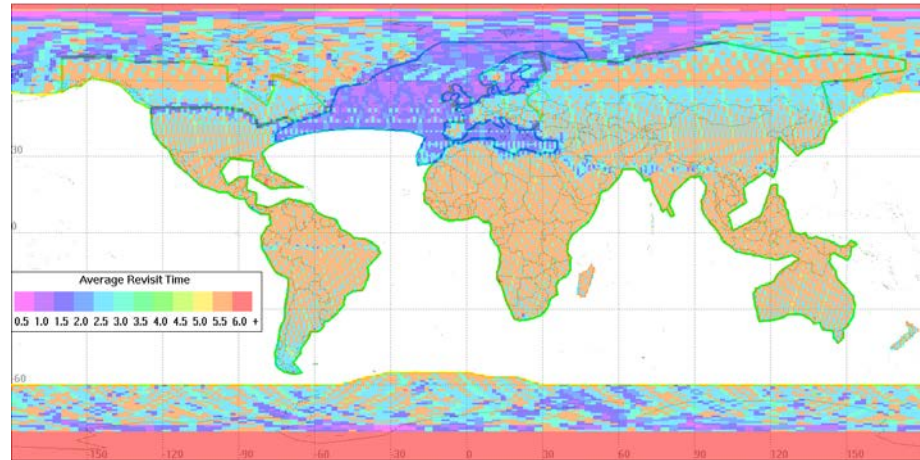


Sentinel-1 Key Requirements



- Provide C-band SAR data continuity of ERS/ENVISAT type of missions at medium resolution (10 m and lower)
- Greatly improved coverage and revisit (i.e. as compared to ENVISAT)
- Conflict-free operations (wide swath and dual-pol modes)
- High system availability (SAR duty cycle and data latency)
- Data quality similar or better than ERS/ENVISAT (e.g. equalized performance across the swath)

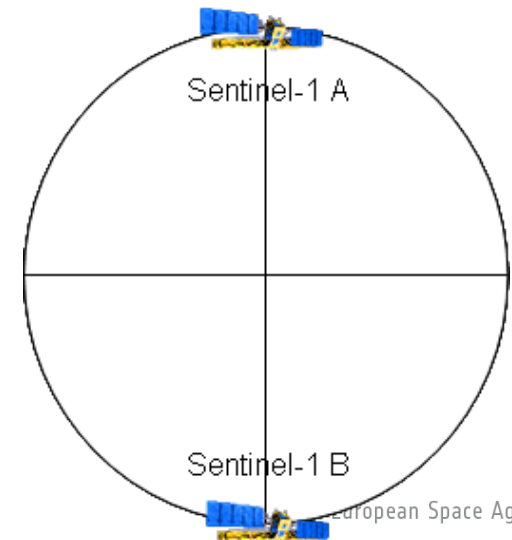
Average Revisit Time with S-1A + S-1B Satellites



Sentinel-1 Mission Facts



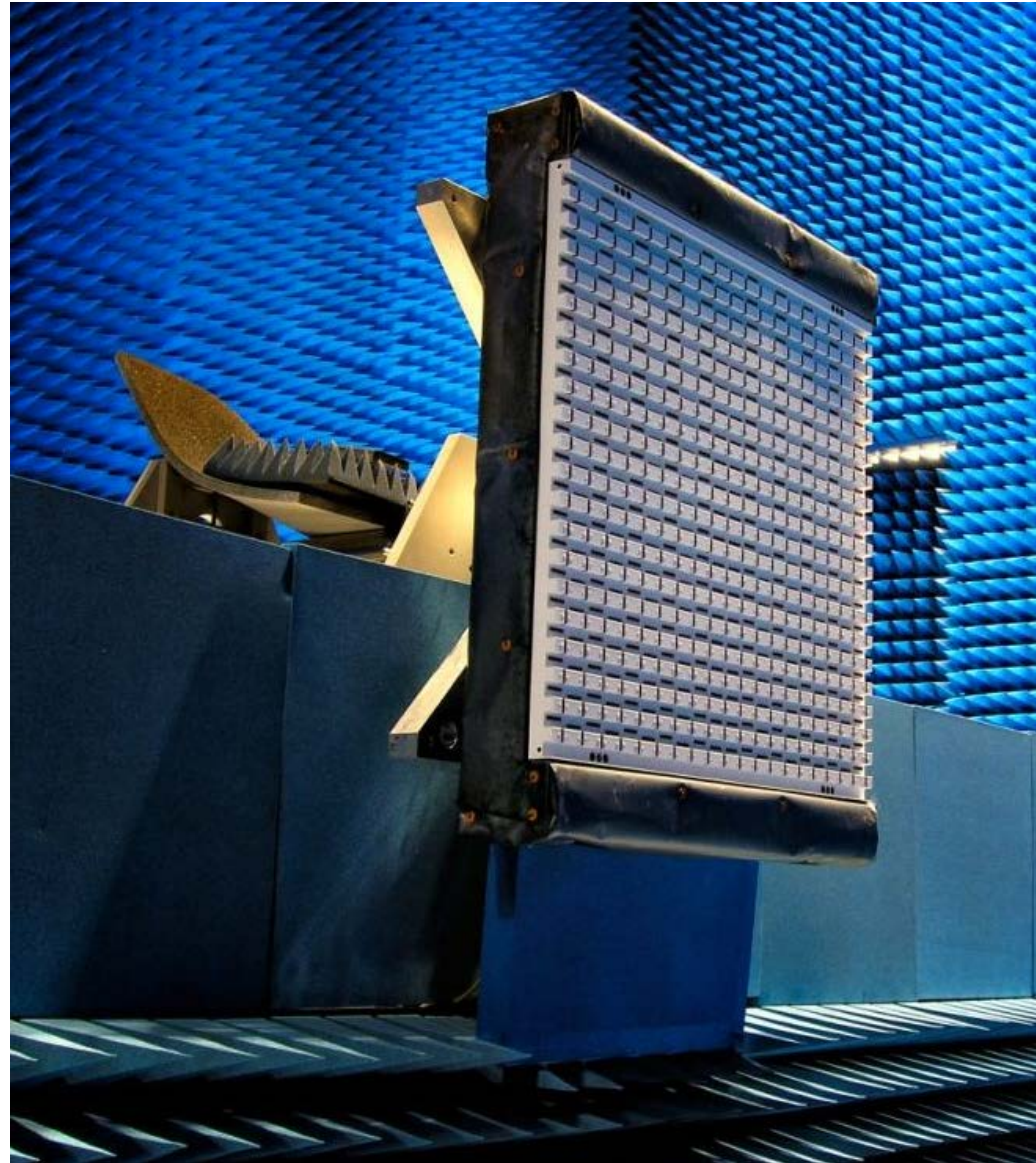
- Constellation of two satellites (A & B units)
- C-Band Synthetic Aperture Radar Payload
- Near-Polar sun-synchronous (dawn-dusk) orbit at 693 km altitude
- Both S-1 satellites are in the same orbit (180 deg. phased in orbit)
- 12 days repeat cycle (1 satellite), 6 days for the constellation
- 7 years design life time with consumables for 12 years
- Launch of Sentinel-1 A scheduled for May 2013 followed by Sentinel-1 B 18 months later



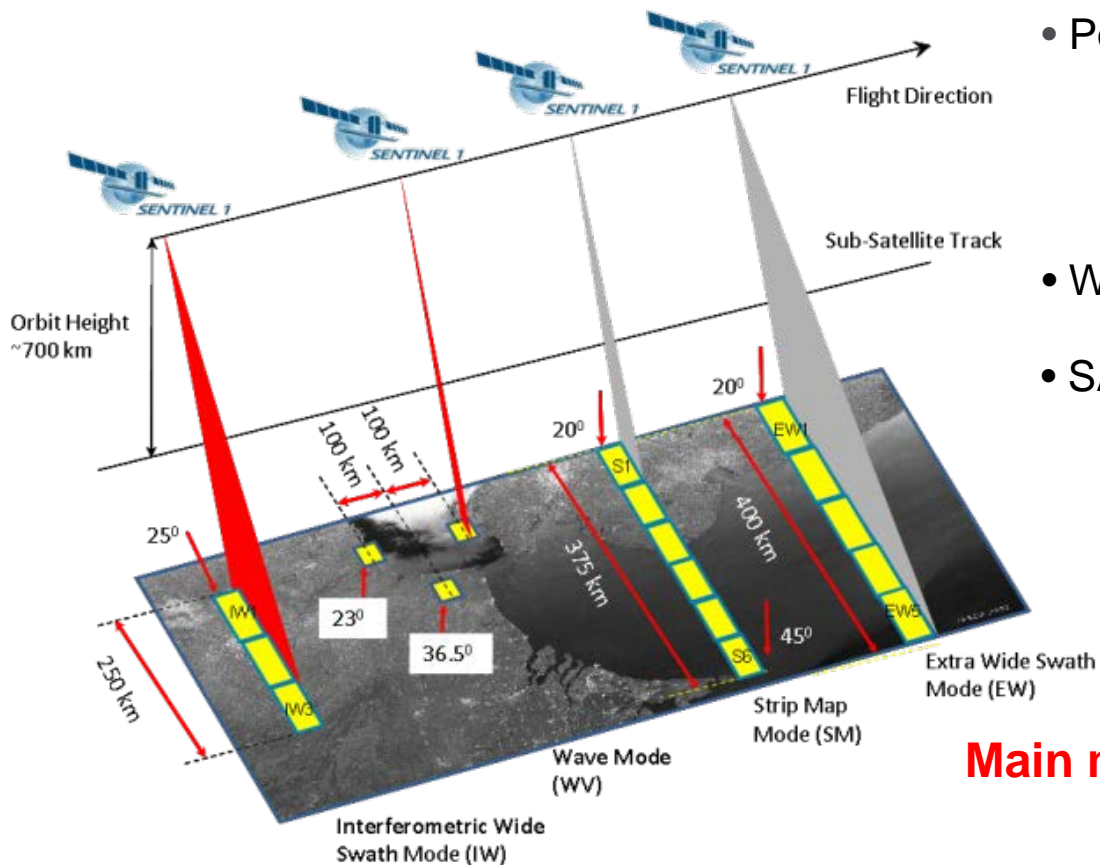
Sentinel-1 Technical Facts



- C-Band SAR instrument operates at centre frequency of 5.405 GHz
- On-board data storage capacity (mass memory) of 1400 Gbit
- Two X-band RF channels for data downlink with 2 X 260 Mbps
- On-board data compression using Flexible Dynamic Block Adaptive Quantization
- Optical Communication Payload for data transfer via laser link with the GEO European Data Relay Satellite (ERDS) system



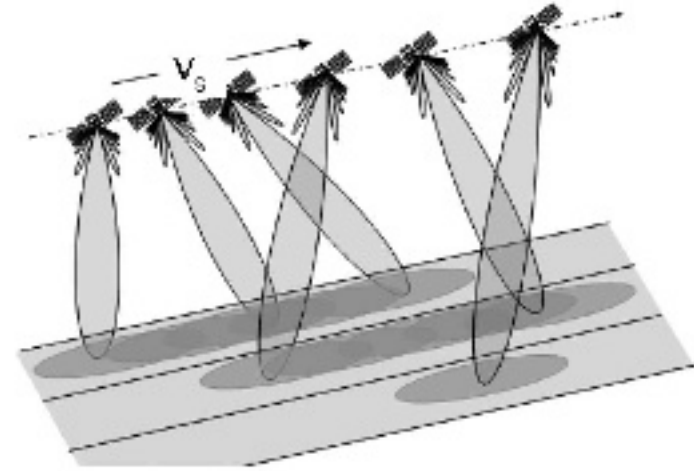
4 mutually exclusive SAR modes with different resolution and coverage



- Polarisation schemes for IW, EW & SM:
 - ✓ single polarisation: HH or VV
 - ✓ dual polarisation: HH+HV or VV+VH
- Wave mode: HH or VV
- SAR duty cycle per orbit:
 - ✓ up to 25 min in any of the imaging modes
 - ✓ up to 74 min in Wave mode

Main modes of operations: IW and WV

1. SM is the continuation of ERS/ASAR Image modes
2. IW and EW modes relies on TOPS⁽¹⁾ acquisition mode combining electronic steering in elevation and azimuth:
 - a. IWS : 3 sub-swath IW1- IW3
 - b. EWS : 5 sub-swath EW1-EW5
3. WV is the continuation of ERS/ASAR WV mission but alternates swath between imagettes.
 - a. same bandwidth as SM, WV



⁽¹⁾ De Zan, F.; Guarnieri, A.M.; , "TOPSAR: Terrain Observation by Progressive Scans," *European Space Agency Geoscience and Remote Sensing, IEEE Transactions on* , vol.44, no.9, pp.2352-2360, Sept. 2006

Challans: TOPSAR image



Time acquisition: July 9th, 2007 at 6.26 am



Courtesy of DLR

Agency

Sentinel-1 SAR Imaging Modes (3/3)



| Mode | Access Angle | Single Look Resolution | Swath Width | Polarisation |
|----------------------------|--------------------------------------|------------------------------------|--|---------------------------|
| Interferometric Wide Swath | > 25 deg. | Range 5 m Azimuth 20 m | > 250 km | HH+HV or VV+VH |
| Wave mode | 23 deg. and 36.5 deg. | Range 5 m Azimuth 5 m | > 20 x 20 km Vignettes at 100 km intervals | HH or VV |
| Strip Map | 20-45 deg. | Range 5 m Azimuth 5 m | > 80 km | HH+HV or VV+VH |
| Extra Wide Swath | > 20 deg. | Range 20 m Azimuth 40 m | > 400 km | HH+HV or VV+VH |

Image Quality Parameters for all Modes (worst case)

| | |
|------------------------------------|--------|
| Radiometric accuracy (3σ) | 1 dB |
| Noise Equivalent Sigma Zero | -22 dB |
| Point Target Ambiguity Ratio | -25 dB |
| Distributed Target Ambiguity Ratio | -22 dB |

High level strategy:

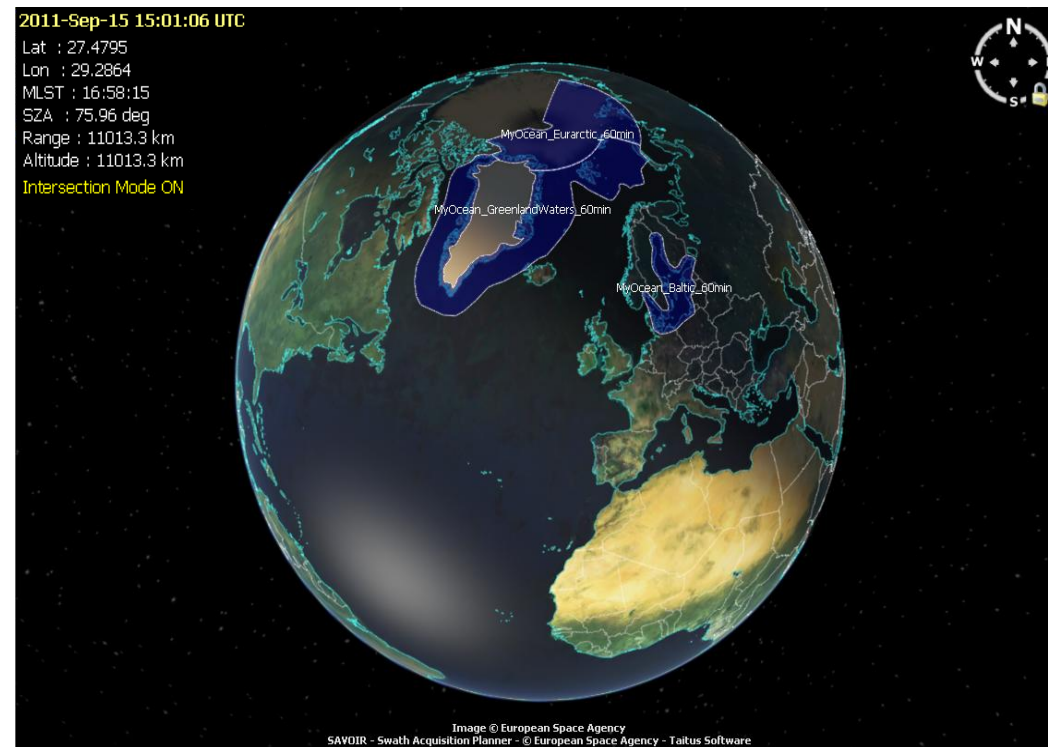
- optimum use of SAR duty cycle (25 min/orbit), taking into account the various constraints (e.g. limitation in the number of X-band RF switches, mode transition times)
- **Wave** Mode continuously operated over open oceans, with lower priority w.r.t. the other high rate modes
- IW or EW modes operated over pre-defined geographical areas:
 - **Over land**: pre-defined mode is **IWS**
 - **Over seas and polar areas, and ocean relevant areas**: pre-defined mode is either **IWS** or **EWS**
- In **exceptional** cases only, **emergency** observation requests may alter the pre-defined observation scenario, with e.g. the use of the Strip Map mode

Preliminary observation requirements from MyOcean sea-ice monitoring services



- **Areas of interest:**
Eurarctic, Baltic sea, Antarctic
- **Data latency** from sensing:
 - NRT 1h for Eurarctic, Baltic sea
 - NRT 1h-3h for Antarctica
- **Mode / polarisation:**
 - EW: 400 km swath, 90m res. (12 ENL)
 - Polarisation:
 - ideally dual-polarisation (HH+HV) for ice charting
 - single polarisation (HH) acceptable for ice drift monitoring in the Arctic Ocean and Antarctic winter season
- **Potential conflicts**, mainly with:
 - EMSA oil spill monitoring services
 - Ship detection services (Baltic sea)
 - Land requirements regarding coastal zones (mode transition)
 - Other “National” services

North Hemisphere

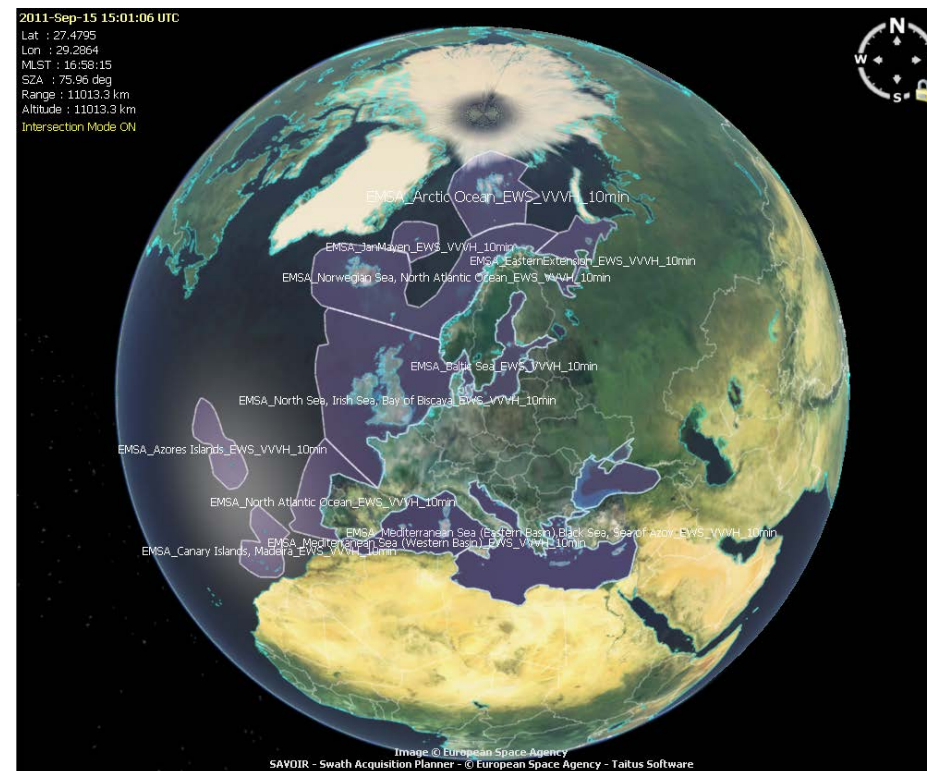


Preliminary observation requirements from EMSA for CleanSeaNet 2nd generation (collaborative)



- **Data latency:**
 - RT / less than 10 min from sensing
- **Mode / polarisation:**
 - EW: 400 km swath, 50m res, TBC
 - IW mode may be privileged over specific areas to improve ship detection service (part of CleanSeaNet-2), e.g. Mediterranean Sea
 - **Polarisation:**
 - ideally dual-polarisation (VV+VH) for oil spill monitoring
 - HH+HV might be acceptable in case of conflicts with other services
 - H polarisation better for ship detection
- **Potential conflicts**, mainly with:
 - Sea-ice monitoring services (MyOcean and National)
 - Ship detection services (National)
 - Land requirements regarding coastal zones (mode transition)
 - Other “National” services

Sentinel-1 RT (10 min)

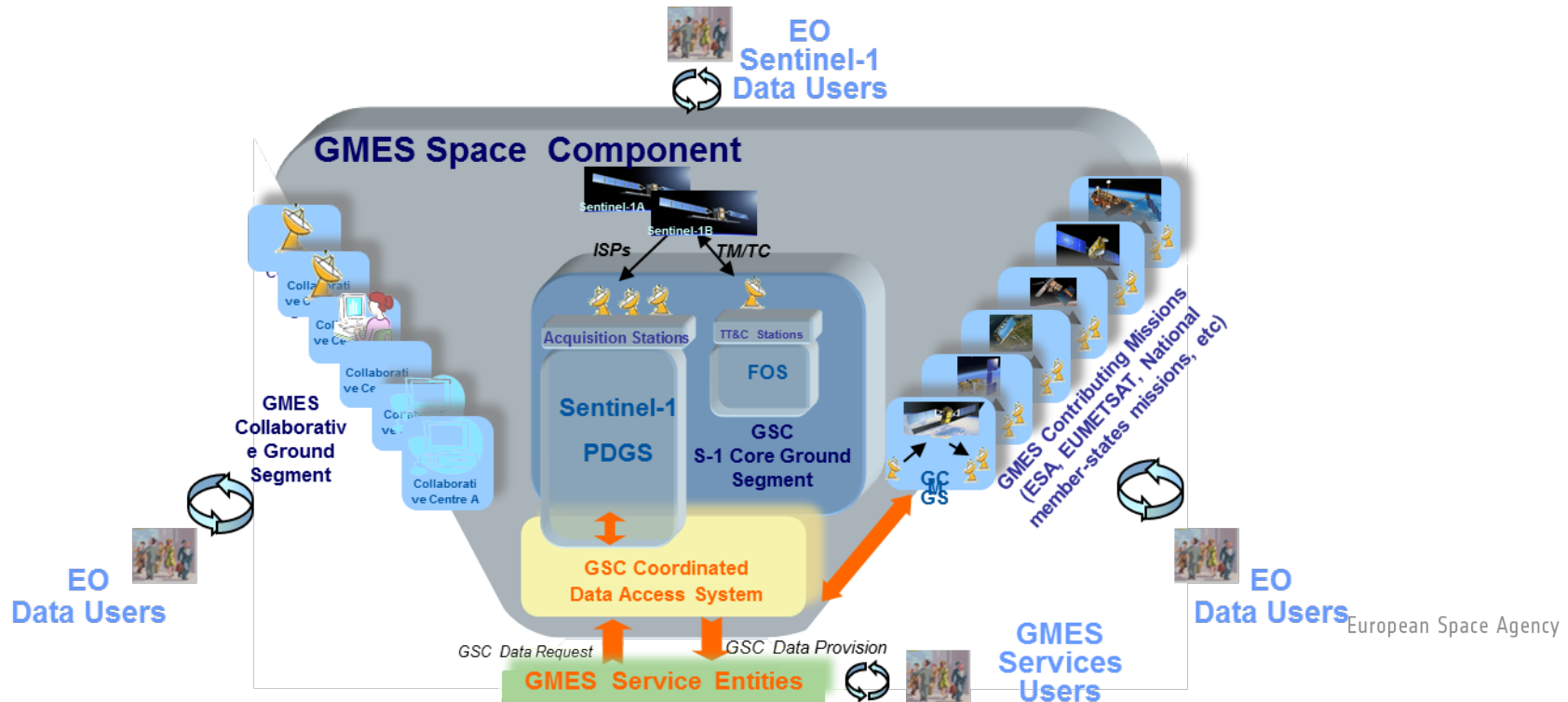


→ Further discussion required with EMSA

Sentinel-1 PDGS Overall Context

GSC Ground Segment consisting of:

- a GSC Core Ground Segment, with GSC-funded functions and operations, providing:
 - the primary access to all Sentinel Missions core products
 - the coordinating access functions to Contributing Missions and Sentinels data
- a GSC Collaborative Ground Segment, with non GSC-funded operations, providing through dedicated operational interfaces:
 - a supplementary access to Sentinel Missions data, i.e. specific services (e.g. with shorter timeliness), or specific products
 - the frame for international cooperation

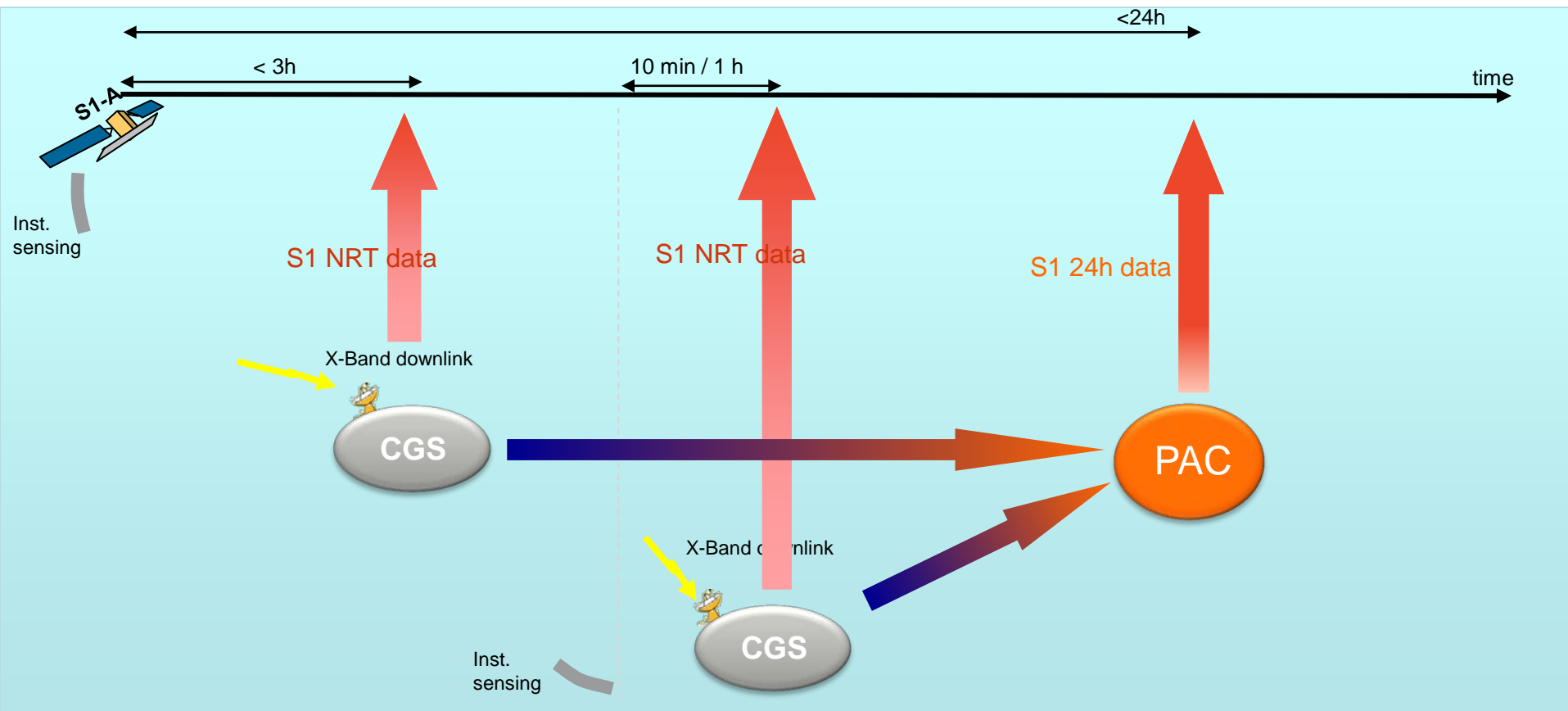


Sentinel-1 PDGS Data Timeliness



Data access to systematically generated products is provided according to the following timeliness:

- Standard timeliness: **within 24h from sensing** for all systematic products
- NRT timeliness:
 - < 3h from sensing (**within 1h from downlink**)
 - < **1h from sensing** for data acquired in direct downlink over specific areas (e.g. European waters).



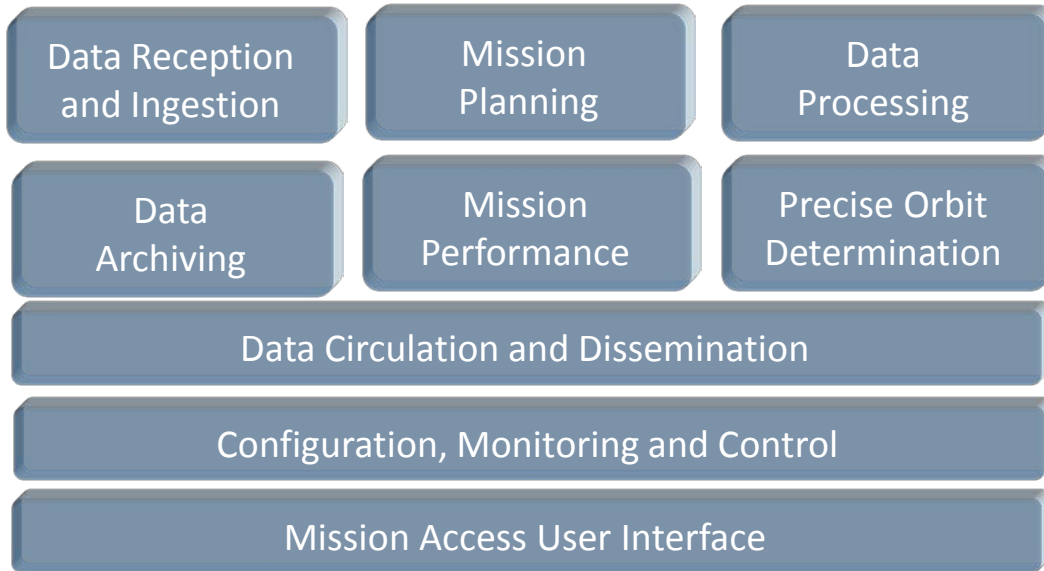
Sentinel-1 PDGS Key Role



X-band raw data



Sentinel-1 PDGS



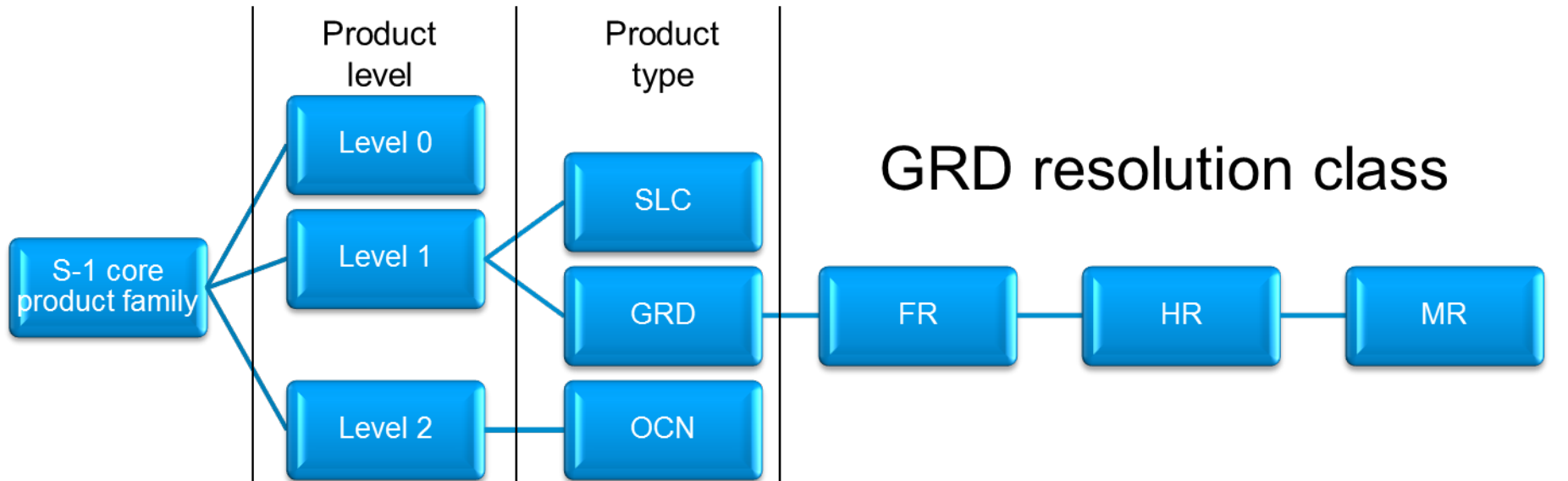
Products



The Sentinel-1 PDGS as a component of the overall GMES Space Component (GSC) Ground Segment, in charge of the following key activities:

- Implementing the Sentinel-1 mission observation scenario
- X-Band data reception
- Generating the operational core ground segment products
- Reacting to emergency orders with rush instrument tasking and processing
- Providing access to Sentinel-1 data
- Ensuring the long term mission data archiving
- Monitoring the instrument and mission performance
- Ensuring Sentinel-1 core operational user products meet the expected quality, with necessary calibration and validation activities

S-1 Product Family



| Acquisition Mode | L0/1/2 | Product type | GRD_FR | GRD_HR | GRD_MR |
|------------------|--------|--------------|--------|--------|--------|
| SM | ✓ | ✓ | ✓ | ✓ | ✓ |
| IW | ✓ | ✓ | | ✓ | ✓ |
| EW | ✓ | ✓ | | ✓ | ✓ |
| WV | ✓ | ✓ | | | |

LEVEL-2 PRODUCT

1. The L2 product family is composed by one **OCEAN (OCN) product** providing up to 3 different components:
 - a. **Ocean Swell spectra (OSW)**: providing continuity with ERS and ASAR WV
 - b. **Ocean Wind Fields (OWI)**: new compared to ASAR
 - c. **Surface Radial Velocities (RVL)**: new compared to ASAR
2. Not all components are applicable to all acquisitions mode

| | OSW | OWI | RVL |
|-------|-----|-----|-----|
| SM | ✓ | ✓ | ✓ |
| WV | ✓ | ✓ | ✓ |
| IW/EW | ✗ | ✓ | ✓ |

✗ The current TOPS (IW/EW) instrument settings (not enough overlap between consecutives bursts) doesn't allow to retrieve swell

- Sentinel-1 data products maintain data quality of ESA's previous SAR missions (ERS-1/-2, ENVISAT ASAR)
 - Continuity in performance for geophysical products
 - Potential to meet *evolving* GMES service needs
- In response to GMES service needs, substantial improvements are integrated into mission design
 - Revisit frequency
 - Coverage
 - Timeliness and reliability of service
 - Conflict free operations

- SAR Oceanography Science users consultation at SEASAR 2012
-> preparation for future EOEP4 - Support to Exploitation of Operational Missions (**SEOM**) - roadmap for R&D activities



→ **SEASAR 2012**

Advances in SAR Oceanography

18-22 June 2012 | Tromsø, Norway



THANKS FOR YOUR ATTENTION

Yves-Louis.Desnos@esa.int
[European Space Agency ESRIN](#)